## TOSHIBA

## GR-200 Series <br> 

Line Differential
Protection IED

## GR-200 series -

The GR-200 Series is Toshiba's next generation of protection and control IED's, designed for transmission/distribution networks and providing a platform for distributed and renewable energy systems and railway applications. Flexible adaptation is enabled using extensive hardware and modular software combinations facilitating an application oriented solution.

## Meeting your needs -

Extensive hardware and modular software combinations provide the flexibility to meet your application and engineering requirements.
Future upgrade paths and minor modifications are readily achievable on demand.

## Powerful and wide application -

In addition to protection \& control, GR-200 has been designed to meet the challenges and take advantage of developments in information \& communications technology.

## APPLICATION

GRL200 line differential protection is implemented on Toshiba's next generation GR-200 Series IED platform and has been designed to provide phase-segregated current differential protection using digital telecommunications, together with control applications. This powerful and user-friendly IED will provide you with the flexibility to meet your application and engineering requirements in addition to offering excellent performance, the high quality and operational peace of mind.

## - Complete EHV/HV Transmission Line Protection package

- Overhead lines or underground cables
- Line differential protection for up to 3 terminals
- Integrated Distance, Directional OC/EF and other voltage/current protections
- Single or parallel lines
- Lines with heavy load current
- Short or long distance lines
- Lines with weak or no in-feed
- Single/three/multiphase tripping facilitating all auto-reclose schemes


## - Communications

- Line differential and teleprotection, direct optical fiber, ITU-T X.21, ITU-T G.703, IEEE Std. C37.94 and Ethernet packet-based communications
- Within substation automation system, IEC 61850-8-1 [Station bus], IEC 60870-5-103 and IEC62439/PRP/HSR



## FEATURES

## - Application

GRL200 can be applied in various EHV/HV network configurations.

- Overhead lines or underground cables
- Two to three-terminal lines
- Lines with weak or no-infeed
- Single or parallel lines
- Lines with heavy load current
- Short or long distance lines
- Functionality
- Eight settings groups
- Automatic supervision
- Metering and recording functions
- Time synchronization by external clock using IRIG-B or system network


## - Communication

- System interface - RS485, Fiber optic, 100BASE-TX/1000BASE-T, 100BASEFX, 1000BASE-LX
- Multi protocol - IEC 60870-5-103, IEC 61850 and IEC62439/PRP/HSR


## FUNCTIONS

- Protection
- Phase-segregated differential protection
- Zero-sequence current differential protection for high resistance earth faults
- Charging current compensation
- Distance protection with four independent zones
- Backup non-directional and directional earth fault command protection
- Non-directional and directional Overcurrent backup protection
- Non-directional and directional negative phase sequence overcurrent protection
- Thermal overload protection
- Broken conductor detection
- Circuit breaker failure protection
- Switch-on-to-fault (SOTF) protection
- Stub fault protection for one-and-a-half breaker system
- Phase to neutral and phase to phase under/overvoltage protection
- Under/overfrequency protection
- Out-of-step protection


## - Security

- Password protection
- Flexibility
- Various models and hardware options for flexible application depending on system requirement and controlled object
- Combined 1A / 5A current inputs
- Multi range DC power supply: 24 to 60 V / 48 to $125 \mathrm{~V} / 110$ to 250 V
- Configurable binary inputs and outputs
- Programmable control, trip and alarm logic with PLC tool software
- Human Machine Interface
- Graphical LCD and 26 LEDs
- Configurable 7 function keys
- USB port for local PC connection
- Direct control buttons for open/close (O/I) and control authority (43R/L)
- Help key for supporting operation
- Monitoring terminals for testing
- Power swing blocking function
- Inrush Current Detector
- Direct transfer trip
- Fail-safe overcurrent scheme
- Control
- Single-shot (single / three / single + three phase / multi-phase) or multi-shot (three phase) autoreclose
- Synchronism voltage check
- Circuit breaker and isolator control
- Switchgear interlock check
- Programmable automatic sequence control


## - Monitoring and Metering

- VT failure detection
- CT failure detection
- Relay address monitoring
- Status and condition monitoring of primary apparatus
- Switchgear operation monitoring
- Plausibility check
- Measurement of I, V, P, Q, PF, f, Wh and varh
- Current and voltage circuit supervision
- Trip circuit supervision
- Fault locator
- HMI function
- Selection of HMI: Standard LCD / large LCD / Separate large LCD
- Large LCD supports Single line diagram indication and touch-type operation.
- 24 configurable tri-state LEDs selectable red/green/yellow
- 7 Programmable function keys for user demand operation
- Recording
- Fault record
- Event record
- Disturbance record


## - Communication

- IEC 60870-5-103 / IEC 61850
- IEC62439 PRP/HSR
- General functions
- Eight settings groups
- Automatic supervision
- Metering and recording functions
- Time synchronization by external clock using IRIG-B or system network
- Password protection for settings and selection of local / remote control
- Checking internal circuit manually.
- Checking internal circuit using monitoring jacks.


## PROTECTION

## - Phase-segregated Protection

GRL200 provides high-speed phase-segregated current differential protection for both phase-to-phase faults and phase-to-earth faults. The phasesegregated current differential protection exhibits high selectivity and sensitivity for all types of faults. It applies a percentage ratio differential characteristic as shown in Figure 1.


Figure 1 Percentage ratio differential element
The characteristic is composed of a small current region and a large current region. When the fault current is large, a large ratio is employed in the large current region of the characteristic, providing stability in the case of external faults accompanied by CT saturation.

Since a high level of sensitivity can be attained with the current differential relay, it can also detect high impedance faults provided that the load current is not too large.

## ■ Zero-sequence Current Differential Protection for High Impedance Earth Faults

Zero-sequence current differential protection can detect high impedance earth faults even with heavy load current. It applies the percentage ratio differential characteristic shown in Figure 2. As the restraining current is the scalar sum of the zero-sequence current at each terminal, the relay sensitivity is not affected by
load current. When the zero-sequence current differential protection operates, it performs timedelayed three- phase tripping.


Id: Differential current $\left(\left|I_{A}+I_{B}+I_{C}\right|\right)$
Ir: Restraining current $\left(\left|\left.\right|_{\mathrm{A}}\right|+\left|\left.\right|_{\mathrm{B}}\right|+|\mathrm{IC}|\right)$ DIFGI: Setting value ik: Minimum operating current

Figure 2 Zero-phase current differential element

## - Charging Current Compensation

When current differential protection is applied to underground cables or long-distance overhead lines, the charging current should be taken into account. It appears as an erroneous differential current in the nofault condition and under external fault conditions. Charging current can be included within the relay setting, but the fault detection sensitivity for an internal fault is reduced as a consequence.

To suppress the effect of the charging current while at the same time maintaining its high fault detection sensitivity, GRL200 has a charging current compensation function which derives the charging current component from the phase current.

The amplitude of the charging current varies with that of the line voltage. If the value of charging current (DIFIC) at the rated line voltage is input, GRL200 calculates and compensates for the charging current at the measured line voltage.

Thus, instead of the phase current la, a compensated current I = la - DIFIC is used for protection at all terminals.

## - Dual Communication

Dual communication mode can be applied to protection of two-terminal lines. Using dual communication mode, it is possible to maintain
continuous operation of the current differential protection in the event of failure of one of the communication channels.


Figure 3 Dual Communication

## - Countermeasure for Through-Fault Current

As shown in Figure 4, for an external fault on a one-and-a-half breaker system, a large fault current IA flows through CT1A and CT2A. If the saturation levels of CT1A and CT2A are different, an erroneous differential current may occur between IA1 and IA2 as a result of CT saturation.

This may cause terminal B to operate incorrectly if it is a weak infeed terminal and the restraining current is small.

To cope with the through-fault current, GRL200 can be set to output tripping commands under the condition that the differential protection operates at both terminals. As the remote current is sent by the result of DIF or each value of CT1 and CT2, GRL200 provide appropriate measurement on basis of CT's configuration.


Figure 4 Through-fault current on one-and-a-half breaker system

## - Stub Protection

Stub protection operates for a fault in a stub zone on a breaker-and-a-half breaker system. With the auxiliary contact of the line disconnector open, only the local terminal current is used as the operating quantity by setting the remote terminal current data to zero.

## Transfer Trip Function

GRL200 provides a transfer trip function which receives a trip signal from the remote terminal and outputs a trip command. Two transfer trip commands are provided. The sending signal is configured by PLC function. If the sending signal is assigned on a per phase basis by PLC, single-phase tripping is available.

## Out-of-Step Protection

By transmitting the phase information of the local voltage to the remote terminal, the out-of-step protection can measure the phase difference between the terminals of a transmission line as illustrated in Figure 5. It detects an out-of-step condition when the difference in the phase angle exceeds $180^{\circ}$, and trips both terminals.

The out-of-step protection can detect an out-of-step condition even with a high rate of slip.


Figure 5 Out-of-step protection element

## - Non-directional and Directional Overcurrent

 and Earth Fault ProtectionGRL200 provides non-directional and directional overcurrent protections with inverse time and definite time characteristics for both phase faults and earth faults.

Inverse time overcurrent protection consists of an IDMT (inverse definite minimum time) element. IDMT is available in conformity with the IEC 60255-151 standard which encompasses both the IEC and IEEE/ANSI standard characteristics. Alternatively, a user-configurable curve may be created.

The IDMT element has a programmable reset feature, selectable for instantaneous, definite time or dependent time operation. This feature can be used to protect against intermittent fault conditions, or to grade correctly with electromechanical overcurrent relays.

Definite time overcurrent protection is enabled by the instantaneous overcurrent element and pickup-delay timer.

Tripping by each element can be disabled by scheme switches, and overcurrent backup protection can be blocked by a binary input signal.

GRL200 can also provide non-directional and directional earth fault protection. Protection functionality is the same as for the phase fault elements.

The directional earth fault elements have a user selectable minimum voltage threshold.

GRL200 can provide directional earth fault command protection by using two-stage directional earth fault elements, of which one is for tripping and the other is for blocking or for current reversal detection.

## - Non-Directional and Directional Sensitive Earth Fault Protection

GRL200 provides non-directional and directional earth fault protection with more sensitive settings for use in applications where the fault current magnitude may be very low.

The sensitive earth fault element includes a digital filter which rejects all harmonics other than the fundamental power system frequency.

The sensitive earth fault quantity is measured directly, using a dedicated core balance earth fault CT.

## - Non-directional and Directional Negative Phase Sequence Overcurrent Protection

Negative phase sequence overcurrent (OCN) protection can be used in applications where certain fault conditions may not be detected by the normal phase and earth overcurrent protections, for example, in the case of a relay applied on the delta side of a delta-star transformer, to detect an earth fault on the star side. Alternatively, OCN can be used to protect a three phase motor against the severe overheating which results from operating with an unbalanced supply.

The negative phase sequence overcurrent elements can be directionalised by polarising against the negative phase sequence voltage.

## Breaker Failure Protection

When an overcurrent element remains in operation longer than a pre-determined length of time following the output of a trip signal the associated circuit breaker is judged to have failed and adjacent circuit breakers can be tripped as a back-up measure.

Two independent timers are available, one of which can be used to control the RETRIP of the original circuit breaker(s). The second timer is used to control the back-tripping of adjacent circuit breakers.

For high-speed protection, an overcurrent element with high-speed reset time is used to prevent a spurious retrip or back-trip following a successful trip or re-trip action.

## - Broken Conductor Detection

The unbalance condition caused by an open circuited conductor is detected by the broken conductor detection function. An unbalance threshold with programmable definite time delay is provided.

## - Thermal Overload Protection

The thermal overload feature provides protection for cables and other plant against the effects of prolonged operation under excess load conditions. A thermal replica algorithm is applied to create a model for the thermal characteristics of the protected plant. The characteristics are exponential functions according to functional standard IEC 60255-149 and take into account the $I^{2} R$ losses due to the specific operational current and the simultaneous cooling effect of the coolant. In this way the tripping time during an overload condition takes the prior level of load current into consideration. An alarm can be set to operate before the tripping condition is reached.
Thermal image:

$$
t=\mathrm{t} / n \frac{I^{2}-I_{p}^{2}}{I^{2}-\left(k I_{B}\right)^{2}}
$$

where
t : Operating time
T : Thermal time constant
I: Overload current
$I_{B} \quad$ Thermal overload current setting
K: Constant
$\mathrm{I}_{\mathrm{p}}$ Specified load current before the overload occurs

## - Overvoltage Protection

GRL200 provides overvoltage protections for both phase-to-phase voltage input and phase-to-neutral voltage input. All stages can be set for inverse time or definite time operation. In total, therefore, GRL200 provides four independent overvoltage thresholds.


Figure 7 Inverse time characteristics

## - Undervoltage Protection

GRL200 provides two-stage undervoltage protection for phase-to-phase voltage input and two-stage undervoltage protection for phase-to-neutral voltage input. The undervoltage protection is provided with an undervoltage blocking function to prevent undervoltage tripping in the case of a dead line.

## - Under/Overfrequency Protection

GRL200 provides over/under frequency protection and frequency rate-of-change protection.

These protections provide independent frequency protection stages. The over/under frequency protection is programmable for either under- or overfrequency operation, and each has an associated DTL timer. The frequency rate-of-change protection calculates the gradient of frequency change ( $\mathrm{df} / \mathrm{dt}$ ).

## - Inrush Current Detector

The inrush current detector is used to prevent an incorrect operation of overcurrent protections from a magnetising inrush current during transformer energisation. Inrush current detector (ICD) detects second harmonic inrush current during transformer energisation.

## Distance Protection

GRL200 provides a distance protection scheme, so realizing a complete line protection capability within a single package It provides six independent distance protection zones, the characteristics of which are shown in the Figure 8 and 9. Individual measurement zones are provided for phase-fault and earth-fault.

(a) Forward zone

(b) Reverse zone

(c) Non directional zone

Figure 8 Quadrilateral Characteristics

(a) Forward zone


Figure 9 Mho-based Characteristics

## - OC/UV and EF Guard Schemes

GRL200 provides OC, OCD, UV, UVS, UVD and EFD elements as additional fault detection criteria to prevent unwanted operation in the unlikely event that a communication failure should go undetected. OC is a phase overcurrent element, OCD is a phase current change detection element, UV is a phase undervoltage element, UVS is phase to phase undervoltage element, UVD is phase voltage change detection element and EFD is a zero-sequence current change detection element.

## Control

## - Autoreclose

Most faults on HV and EHV overhead transmission lines are transient faults, which are removed following line de-energization. After a short time, the hot gases disperse and the air de-ionizes. After clearing the fault and de-ionizing the fault arc, reclosing can be performed. GRL200 provides two autoreclose schemes, single-shot autoreclose and multi-shot autoreclose.

GRL200's autoreclose function can be initiated by any of the following high-speed protections.

- Protection using telecommunication
- Distance zone is set to zone 1 extension


## Single-shot autoreclose

Single-shot reclosing can provide any of three autoreclose modes; single-phase autoreclose, three-phase autoreclose, single-and three-phase autoreclose and multi-phase autoreclose.

In the single-phase autoreclose mode, only a faulted phase is tripped, and then reclosed if a single-phase earth fault occurs.

In the three-phase autoreclose mode, all three phases are tripped, and then reclosed regardless of the fault mode, whether a single-phase fault or a multi-phase fault has occurred.

In the single- and three-phase autoreclose mode, the single-phase is reclosed if a single-phase is tripped and the three phases are reclosed if three phases are tripped.

Multi-phase autoreclose mode can be applied to double-circuit lines. In this mode, only the faulted phases are tripped and reclosed when the terminals of double-circuit lines are interconnected during the dead time through at least two or three different phases.

## - Multi-shot autoreclose

In a multi-shot autoreclose, two- to five-shot reclosing can be selected. The first shot is selected from any of the five autoreclose modes available in the single-shot autoreclose scheme.

If reclosing by the first shot fails, three-phase tripping and reclosing is applied for the second to fifth shots.

## Synchronism Check

For the correct operation of three-phase autoreclose, voltage and synchronism check are necessary. The characteristics of the synchronism check element are shown in Figure 10.

A detected slip cycle is determined by the following equation:
where, $\mathrm{f}=\overline{180^{\circ} \text { XTSYN }}$
f: slip cycle
$\theta$ : synchronism check angle setting
TSYN: synchronism check timer setting


Figure 10 Synchronism check element

## ■ One-and-a-half Breaker Scheme

GRL200 performs two-breaker autoreclose in a one-and- a-half breaker scheme.

Only single-shot autoreclose is available in a one-and- a-half breaker scheme. Single-phase autoreclose, three-phase autoreclose or single and three-phase autoreclose can be applied to the two circuit breakers.

## - Interfaces with Telecommunication Systems

Current data sampled at the local terminal is transmitted to the remote terminal(s) via the telecommunication system.

GRL200 can be provided with the following interface(s) and linked to a dedicated optical fibre communication circuit or multiplexed communication circuit (multiplexer) shown in Figure 11.

a) Optical interface

b) Optical interface using multiplexer

c) Optical interface using multiplexer

Figure 11 Telecommunication system

## Switchgear Control

GRL200 provides functions for local control of switchgear from the HMI. Two-stepped operation (select-control) is applied for the control of circuit breakers, isolator switches and earthing switches.

Also, switchgear control commands from the station level can be performed through GRL200 within the application of a substation automation control system.

## - Interlock check

The interlocking function blocks the operation of primary switching devices, for instance when an isolator switch is under load, in order to prevent equipment damage and/or accidental human injury.

Each switchgear control function has interlocking modules included for different switchyard arrangements, where each function handles interlocking for one bay. The interlocking function is distributed to each IED and is not dependent on any central function.

## HMI FUNCTION

## - Front Panel

GRL200 provides the following front panel options.

- Standard LCD
- Large LCD (optional separate LCD type is also available)

The standard LCD panel incorporates the user interfaces listed below. Setting the relay and viewing stored data are possible using the Liquid Crystal Display (LCD) and operation keys.

- 21 character, 8 line LCD with back light
- Support of English language

The large LCD panel incorporates a touch type screen for control and navigation purposes.

- 40 character, 40 line LCD with back light


Figure 12 - HMI Panel

The local human machine interface includes an LCD which can display the single line diagram for the bay.

The local human machine interface is simple and easy to understand with the following facilities and indications.

- Status indication LEDs (IN SERVICE, ERROR and 24 configurable LEDs)
- 7 Function keys for control, monitoring, setting group change and screen jump functions of which operation is configurable by the user
- Test terminals which can monitor three different signals from the front panel without connection to the rear terminals.
- USB port


## - Local PC connection

The user can communicate with GRL200 from a local PC via the USB port on the front panel. Using GR-200 series engineering tool software (called GR-TIEMS), the user can view, change settings and monitor realtime measurements.

## MONITORING

## - Metering

The following power system data is measured continuously and can be displayed on the LCD on the relay fascia, and on a local or remotely connected PC.

- Measured analog voltages, currents, frequency, active- and reactive-power

The accuracy of analog measurement is $\pm 0.5 \%$ for $\mathrm{I}, \mathrm{V}$, $P, Q$ at rated input and $\pm 0.03 \mathrm{~Hz}$ for frequency measurement.

## Status Monitoring

The open or closed status of each switchgear device and failure information concerning power apparatus and control equipment can be monitored by GRL200.

Both normally open and normally closed contacts are used to monitor switchgear status. If an unusual status is detected, a switchgear abnormality alarm is generated.

## RECORDING

## - Event Record

Continuous event-logging is useful for monitoring of the system from an overview perspective and is a complement to specific disturbance recorder functions. Up to 1,024 time-tagged events are stored with 1 ms resolution.

## Fault records

Information about the pre-fault and fault values for currents and voltages are recorded and displayed for trip event confirmation. The most recent 8 time-tagged faults with 1 ms resolution are stored. Fault record items are as follows.

- Date and time
- Faulted phase
- Tripping phase
- Operating mode
- Pre-fault and post-fault current and voltage data (phase, phase to phase, symmetrical components)
- Autoreclose operation
- Fault location

Fault location is initiated by relay tripping signals. It can also be started on receipt of a start signal from external relays.

Fault location is indicated in km, mile and \% for the whole length of the protected line. The fault location is highly accurate for parallel lines due to the implementation of zero-sequence mutual impedance compensation.

The result of the fault location is stored as fault record data.

## Disturbance records

The Disturbance Recorder function supplies fast, complete and reliable information for disturbances in the power system. It facilitates understanding of system behavior and performance of related primary and secondary equipment during and after a disturbance.

The Disturbance Recorder acquires sampled data from all selected analogue input and binary signals. The data is stored in COMTRADE format.

## COMMUNICATION

## - Station bus

Ethernet port(s) for the substation communication standards IEC 61850 is provided for the station bus. GRL200 also support Ethernet redundancy scheme protocols defined in the IEC 62439-3 standard: PRP/HSR.

## Serial communication

Serial ports (RS485 and fiber optic) for communicating with legacy equipment or protection relays over IEC 60870-5-103 protocol are provided. The GRL200 can function as a protocol converter to connect to SAS.

## GENERAL FUNCTION

## - Self supervision

Automatic self-supervision of internal circuits and software is provided. In the event of a failure being detected, the ALARM LED on the front panel is illuminated, the 'UNIT FAILURE' binary output operates, and the date and time of the failure is recorded in the event record.

## Time synchronization

Current time can be provided with time synchronization via the station bus by SNTP (Simple Network Time Protocol) with the IEC 61850 protocol. IRIG-B port is also available as an option.

## - Setting groups

8 settings groups are provided, allowing the user to set one group for normal conditions, while the other groups may be set to cover alternative operating conditions.

## Password protection

Password protection is available for the execution of setting changes, executing control, clearing records and switching between local/remote control.

## - Simulation and test

GRL200 provides simulation and test functions to check control functions without modification to wiring provided by a dummy circuit breaker (virtual equipment), and the capability to test communication signals by forced signal status change.

The simulation and test can work in the Test mode only.

## TOOLS \& ACCESSORY

The PC interface GR-TIEMS allows users to access GRL200 and other Toshiba GR-200 series IEDs from a local personal computer (PC) to view on-line or stored data, to change settings, to edit the LCD screen, to configure sequential logics and for other purposes.

## REMOTE SETTING AND MONITORING

The engineering tool supports functions to change settings and to view and analyze fault and disturbance records stored in GRL200. Waveform data in the disturbance records can be displayed, edited, measured and analyzed in detail. An advanced version of the engineering tool can provide additional and powerful analysis tools and setting calculation support functions.


Figure 13 PC Display of GR-TIEMS

## LCD CONFIGURATION

The user can configure and customize the MIMIC data displayed on the LCD of GRL200 using GR-TIEMS software.


Figure 14 PC Display of MIMIC configuration

## PROGRAMMABLE LOGIC EDITOR

The programmable logic capability allows the user to configure flexible logic for customized application and operation. Configurable binary inputs, binary outputs and LEDs are also programmed by the programmable logic editor. This complies with IEC61131-3 standard.


Figure 15 PC display of PLC editor

TECHNICAL DATA

| Analog Inputs |  |
| :---: | :---: |
| Rated current In <br> Rated voltage Vn <br> Rated Frequency <br> Overload Rating <br> Current inputs <br> Voltage inputs | 1A or 5A (selectable) <br> 100 V to 120 V <br> 50 Hz or 60 Hz (specified when order) <br> 4 times rated current continuous <br> 5 times rated current for 3 mins <br> 6 times rated current for 2 mins <br> 30 times rated current for 10 sec <br> 100 times rated current for 1 second <br> 250 times rated current for one power cycle ( 20 or 16.6 ms ) <br> 2 times rated voltage continuous <br> 2.5 times rated voltage for 1 second |
| Burden <br> Phase current inputs <br> Earth current inputs <br> Sensitive earth fault inputs Voltage inputs | $\begin{aligned} & \leq 0.1 \mathrm{VA} \text { at } \ln =1 \mathrm{~A}, \quad \leq 0.2 \mathrm{VA} \text { at } \ln =5 \mathrm{~A} \\ & \leq 0.3 \mathrm{VA} \text { at } \mathrm{In}=1 \mathrm{~A}, \quad \leq 0.4 \mathrm{VA} \text { at } \ln =5 \mathrm{~A} \\ & \leq 0.3 \mathrm{VA} \text { at } \mathrm{In}=1 \mathrm{~A}, \quad \leq 0.4 \mathrm{VA} \text { at } \ln =5 \mathrm{~A} \\ & \leq 0.1 \mathrm{VA} \text { at } \mathrm{Vn} \end{aligned}$ |
| Power Supply |  |
| Rated auxiliary voltage | 24/48/60Vdc (Operative range: $19.2-72 \mathrm{Vdc}$ ), <br> $110 / 250 \mathrm{Vdc}$ or $100 / 220 \mathrm{Vac}$ (Operative range: $88-300 \mathrm{Vdc}$ or $80-230 \mathrm{Vac}$ ) <br> <Notes> <br> 1) Binary inputs are intended for use with DC power source only. <br> 2) The power supply supervision function is intended for use with DC power source only. It should be disabled when AC power supply is applied in order to prevent spurious alarms. |
| Superimposed AC ripple on DC supply | $\leq 15 \%$ |
| Power supply interruption withstand period (IEC 60255-11) | 24/48/60Vdc rating: 20 ms <br> $110 / 125 \mathrm{Vdc}$ rating: 50 ms |
| Power consumption | $\leq 15 \mathrm{~W}$ (quiescent) <br> $\leq 25 \mathrm{~W}$ (maximum) |
| Binary Inputs |  |
| Input circuit DC voltage | 24/48/60Vdc (Operating range: $19.2-72 \mathrm{Vdc}$ ), <br> $110 / 125 / 220 / 250 \mathrm{Vdc}$ (Operating range: $88-300 \mathrm{Vdc}$ ) <br> Note: Threshold setting is available to BI2 (Setting range: 14 V to 154 V ) |
| Capacitive discharge immunity | $10 \mu \mathrm{~F}$ charged to maximum supply voltage and discharged into the input terminals, according to ENA TS 48-4 with an external resistor |
| Maximum permitted voltage <br> Power consumption | 72 Vdc for $24 / 48 / 60 \mathrm{Vdc}$ rating, <br> 300 Vdc for $110 / 250 \mathrm{Vdc}$ rating <br> $\leq 0.5 \mathrm{~W}$ per input at 220 Vdc |


| Binary Outputs |  |
| :---: | :---: |
| Fast operating contacts Make and carry <br> Break <br> Operating time | 5A continuously <br> $30 \mathrm{~A}, 290 \mathrm{Vdc}$ for 0.2 s ( $\mathrm{L} / \mathrm{R}=5 \mathrm{~ms}$ ) <br> $0.15 \mathrm{~A}, 290 \mathrm{Vdc}(\mathrm{L} / \mathrm{R}=40 \mathrm{~ms})$ <br> Typically 3 ms |
| Semi-fast operating contacts Make and carry <br> Break <br> Operating time | 8A continuously <br> $30 \mathrm{~A}, 240 \mathrm{Vdc}$ for $1 \mathrm{~s}(\mathrm{~L} / \mathrm{R}=5 \mathrm{~ms})$ <br> $0.1 \mathrm{~A}, 250 \mathrm{Vdc}(\mathrm{L} / \mathrm{R}=40 \mathrm{~ms})$ <br> $0.2 \mathrm{~A}, 125 \mathrm{Vdc}(\mathrm{L} / \mathrm{R}=40 \mathrm{~ms})$ <br> Typically 6 ms |
| Auxiliary contacts Make and carry <br> Break <br> Operating time | 8A continuously <br> $30 \mathrm{~A}, 240 \mathrm{Vdc}$ for 1 s (L/R=5ms) <br> $0.1 \mathrm{~A}, 250 \mathrm{Vdc}(\mathrm{L} / \mathrm{R}=40 \mathrm{~ms})$ <br> $0.2 \mathrm{~A}, 125 \mathrm{Vdc}(\mathrm{L} / \mathrm{R}=40 \mathrm{~ms})$ <br> Typically 8 ms |
| Hybrid contacts (10 A breaking) Make and carry <br> Break <br> Operating time | 8A continuously <br> $10 \mathrm{~A}, 220 \mathrm{Vdc}$ for 0.5 s ( $\mathrm{L} / \mathrm{R}=5 \mathrm{~ms}$ ) <br> 10A, 220Vdc (L/R=20ms) <br> $10 \mathrm{~A}, 110 \mathrm{Vdc}(\mathrm{L} / \mathrm{R}=40 \mathrm{~ms})$ <br> 1 ms |
| Durability | $\geq 10,000$ operations (loaded contact) <br> $\geq 100,000$ operations (unloaded contact) |
| Measuring input capability |  |
| Full scale <br> Standard current input Sensitive current input Voltage input <br> Sampling rate <br> Frequency response | $\begin{aligned} & \geq 60 \mathrm{~A}(1 \mathrm{~A} \text { rating) or } 300 \mathrm{~A} \text { ( } 5 \mathrm{~A} \text { rating) } \\ & \geq 3 \mathrm{~A} \text { ( } 1 \mathrm{~A} \text { rating) or } 15 \mathrm{~A} \text { ( } 5 \mathrm{~A} \text { rating) } \\ & \geq 200 \mathrm{~V} \\ & 48 \text { samples / cycle } \\ & <5 \% \text { deviation over range } 16.7 \mathrm{~Hz} \text { to } 600 \mathrm{~Hz} \end{aligned}$ |
| Mechanical Design |  |
| Installation <br> Weight <br> Case color | Flush mounting <br> Approx. 12 kg ( $1 / 2$ size), 15 kg ( $3 / 4$ size), 25 kg ( $1 / 1$ size) <br> 2.5Y7.5/1 (approximation to Munsell value) |
| LED |  |
| Number Color | 26 (Fixed for "In service" and "ERROR") <br> Red / Yellow / Green (configurable) except "In service (green)" and "Error (red)" |
| Function keys |  |
| Number | 7 |
| Local Interface |  |
| USB <br> Maximum cable length | Type B 2m (max.) |
| Terminal Block |  |
| CT/VT input <br> Binary input, Binary output | M3.5 Ring terminal <br> Compression plug type terminal |


| System Interface (rear port) |  |
| :---: | :---: |
| 100BASE-TX/1000BASE-T <br> Cable type <br> Connector type | For IEC 61850-8-1 and GR-TIEMS <br> CAT5e STP cable <br> - enhanced category 5 with Shielded Twisted Pair cable RJ-45 |
| 100BASE-FX <br> Cable type <br> Connector type <br> Wave length | For IEC 61850-8-1 <br> Multimode fibre, $50 / 125 \mu \mathrm{~m}$ or $62.5 / 125 \mu \mathrm{~m}$ <br> SC duplex <br> 1300nm |
| 1000BASE-LX <br> Cable type <br> Connector type Wave length | For IEC 61850-8-1 <br> Single-mode fibre LC duplex 1310nm |
| RS485 <br> Cable type Connector type | For IEC 60870-5-103 <br> Shielded twisted pair cable <br> Push-in spring terminal (PCB connector) |
| Fiber optical (for serial communication) <br> Cable type <br> Connector type <br> Wave length | For IEC 60870-5-103 <br> Multimode fibre, $50 / 120 \mu \mathrm{~m}$ or $62.5 / 125 \mu \mathrm{~m}$ ST <br> 820nm |
| IRIG-B (for time synchronization) <br> Cable type <br> Connector type | Shielded twisted pair cable <br> Push-in spring terminal (PCB connector) |
| Telecommunication Interface for Protection Signalling |  |
| Optical interface (2 km class) <br> Type of fibre <br> Connector type <br> Wave length <br> Optical transmitter <br> Optical receiver <br> Optical interface ( 30 km class) <br> Type of fibre <br> Connector type <br> Wave length <br> Optical transmitter <br> Optical receiver <br> Optical interface (80 km class) <br> Type of fibre <br> Connector type <br> Wave length <br> Optical transmitter <br> Optical receiver | Graded-index multi-mode $50 / 125 \mu \mathrm{~m}$ or $62.5 / 125 \mu \mathrm{~m}$ <br> ST type <br> 820nm <br> LED, more than $-19 \mathrm{dBm}(50 / 125 \mu \mathrm{~m})$, $-16 \mathrm{dBm}(62.5 / 125 \mu \mathrm{~m})$ <br> PIN diode, less than -24 dBm <br> Single mode $10 / 125 \mu \mathrm{~m}$ <br> Duplex LC <br> 1310nm <br> Laser, more than -13 dBm <br> PIN diode, less than -30 dBm <br> DSF $8 / 125 \mu \mathrm{~m}$ <br> Duplex LC <br> 1550nm <br> Laser, more than -5 dBm <br> PIN diode, less than -34 dBm |

ENVIRONMENTAL PERFORMANCE
Atmospheric Environment

| Temperature | IEC 60068-2-1/2 <br> IEC 60068-2-14 | Operating range: $-10^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}$. <br> Storage / Transit: $-25^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$. <br> Cyclic temperature test as per IEC 60068-214 |
| :---: | :---: | :---: |
| Humidity | IEC 60068-2-30 <br> IEC 60068-2-78 | 56 days at $40^{\circ} \mathrm{C}$ and $93 \%$ relative humidity. Cyclic temperature with humidity test as per IEC 60068-2-30 |
| Enclosure Protection | IEC 60529 | IP52 - Dust and Dripping Water Proof IP20 for rear panel |
| Mechanical Environment |  |  |
| Vibration | IEC 60255-21-1 | Response - Class 1 <br> Endurance - Class 1 |
| Shock and Bump | IEC 60255-21-2 | Shock Response Class 1 <br> Shock Withstand Class 1 <br> Bump Class 1 |
| Seismic | IEC 60255-21-3 | Class 1 |
| Electrical Environment |  |  |
| Dielectric Withstand | IEC 60255-27 | 2 kV rms for 1 minute between all terminals and earth. <br> 2 kV rms for 1 minute between independent circuits. <br> 1 kVrms for 1 minute across normally open contacts. |
| High Voltage Impulse | IEC 60255-27 <br> IEEE C37.90 | Three positive and three negative impulses of 5 kV (peak), $1.2 / 50 \mu \mathrm{~s}, 0.5 \mathrm{~J}$ between all terminals and between all terminals and earth. |
| Voltage Dips, Interruptions, Variations and Ripple on DC supply | IEC 60255-11, IEC 61000-4-29, IEC 61000-4-17 IEC 60255-26 Ed 3 | 1. Voltage dips: <br> $0 \%$ residual voltage for 20 ms <br> $40 \%$ residual voltage for 200 ms <br> $70 \%$ residual voltage for 500 ms <br> 2. Voltage interruptions: <br> $0 \%$ residual voltage for 5 s <br> 3. Ripple: <br> $15 \%$ of rated d.c. value, $100 / 120 \mathrm{~Hz}$ <br> 4. Gradual shut-down / start-up: 60 s shut-down ramp, 5 min power off, 60 s start-up ramp <br> 5. Reversal of d.c. power supply polarity: 1 min |
| Capacitive Discharge | ENA TS 48-4 | $10 \mu \mathrm{~F}$ charged to maximum supply voltage and discharged into the input terminals with an external resistance |

## Electromagnetic Environment

| High Frequency Disturbance / Damped Oscillatory Wave | IEC 60255-22-1 Class 3, IEC 61000-4-18 IEC 60255-26 Ed 3 | 1 MHz burst in common / differential modes Auxiliary supply and I/O ports: $2.5 \mathrm{kV} / 1 \mathrm{kV}$ Communications ports: $1 \mathrm{kV} / 0 \mathrm{kV}$ |
| :---: | :---: | :---: |
| Electrostatic Discharge | IEC 60255-22-2 Class 4, IEC 61000-4-2 <br> IEEE C37.90.3-2001 <br> IEC 60255-26 Ed 3 | Contact: 2, 4, 6, 8kV Air: 2, 4, 8, 15kV |
| Radiated RF <br> Electromagnetic <br> Disturbance | IEC 60255-22-3, <br> IEC 61000-4-3 Level 3 <br> IEC 60255-26 Ed 3 | Sweep test ranges: 80 MHz to 1 GHz and 1.4 GHz to 2.7 GHz . <br> Spot tests at 80, 160, 380, 450, 900, 1850 and 2150 MHz . <br> Field strength: $10 \mathrm{~V} / \mathrm{m}$ |
|  | IEEE C37.90.2-1995 | Field strength $35 \mathrm{~V} / \mathrm{m}$ for frequency sweep of 25 MHz to 1 GHz . |
| Fast Transient Disturbance | IEC 60255-22-4 <br> IEC 61000-4-4 <br> IEC 60255-26 Ed 3 | $5 \mathrm{kHz}, 5 / 50 \mathrm{~ns}$ disturbance <br> Auxiliary supply and input / output ports: 4 kV <br> Communications ports: 2 kV |
| Surge Immunity | IEC 60255-22-5 <br> IEC 61000-4-5 <br> IEC 60255-26 Ed 3 | $1.2 / 50 \mu \mathrm{~ms}$ surge in common/differential modes: <br> Auxiliary supply and input / output ports: 4, $2,1,0.5 \mathrm{kV} / 1,0.5 \mathrm{kV}$ <br> Communications ports: up to $1,0.5 \mathrm{kV} / 0 \mathrm{kV}$ |
| Surge Withstand | IEEE C37.90.1-2002 | 3 kV , 1 MHz damped oscillatory wave <br> $4 \mathrm{kV}, 5 / 50 \mathrm{~ns}$ fast transient |
| Conducted RF <br> Electromagnetic <br> Disturbance | IEC 60255-22-6 <br> IEC 61000-4-6 <br> IEC 60255-26 Ed 3 | Sweep test range: 150 kHz to 80 MHz <br> Spot tests at 27 and 68 MHz . <br> Voltage level: 10 V r.m.s |
| Power Frequency Disturbance | IEC 60255-22-7 <br> IEC 61000-4-16 <br> IEC 60255-26 Ed 3 | $50 / 60 \mathrm{~Hz}$ disturbance for 10 s in common / differential modes <br> Binary input ports: $300 \mathrm{~V} / 150 \mathrm{~V}$ |
| Power Frequency Magnetic Field | IEC 61000-4-8 Class 4 IEC 60255-26 Ed 3 | Field applied at $50 / 60 \mathrm{~Hz}$ with strengths of: 30A/m continuously, 300A/m for 1 second. |
| Conducted and Radiated Emissions | IEC 60255-25 <br> EN 55022 Class A, <br> EN 61000-6-4 <br> IEC 60255-26 Ed 3 | Conducted emissions: <br> 0.15 to $0.50 \mathrm{MHz}:<79 \mathrm{~dB}$ (peak) or $<66 \mathrm{~dB}$ (mean) <br> 0.50 to $30 \mathrm{MHz}:<73 \mathrm{~dB}$ (peak) or $<60 \mathrm{~dB}$ (mean) <br> Radiated emissions <br> 30 to $230 \mathrm{MHz}:<40 \mathrm{~dB}(\mathrm{uV} / \mathrm{m})$ <br> 230 to $1000 \mathrm{MHz}:<47 \mathrm{~dB}(\mathrm{uV} / \mathrm{m})$ <br> Measured at a distance of 10 m |

European Commission Directives

| $2014 / 30 / E U$ | Compliance with the European Commission <br> Electromagnetic Compatibility Directive is <br> demonstrated according to EN 60255-26:2013. |  |
| :--- | :--- | :--- |
|  | $2014 / 35 / E U$ | Compliance with the European Commission Low <br> Voltage Directive for electrical safety is <br> demonstrated according EN 60255-27:2014. |


| Performance and Functional Standards |  |
| :--- | :--- |
| Category | Standards |
| General | IEC 60255-1 |
| Common requirements | IEC 60255-24 / IEEE C37.111 (COMTRADE) <br> IEEE C37.239 (COMFEDE) |
| Data Exchange | IEC 60255-27 |
| Product Safety |  |

## Interface Converter GIF200

| Ratings |  |  |
| :---: | :---: | :---: |
| Power supply: |  | 24Vdc - 250Vdc <br> (Operative range: 19.2-300Vdc) less than 8 W |
| Interface |  |  |
| Communication interface <br> Operative Range: <br> Wavelength: <br> Connector type: <br> Fibre type: |  | ```ITU-T G.703 (64kbps, co-directional) ITU-T G. }703\mathrm{ (64kbps, contra-directional or centralized clock) less than 2km 820nm ST 62.5/125\mum Gl fibre``` |
| Atmospheric Environment |  |  |
| Temperature <br> Humidity Enclosure Protection | $\begin{aligned} & \text { IEC60068-2-1/2 } \\ & \text { IEC60068-2-78 } \\ & \text { IEC60529 } \end{aligned}$ | Operating range: $-10^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}$. <br> Storage / Transit: $-25^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$. <br> 56 days at $40^{\circ} \mathrm{C}$ and $93 \%$ relative humidity. IP20 |

FUNCTIONAL DATA

| Phase-segregated Current Differential Protection |  |
| :---: | :---: |
| DIFI1 (Small current region) | 0.10 to 2.00 A in 0.01 A steps (1A rating) 0.50 to 10.00 A in 0.01 A steps ( 5 A rating) |
| DIFI2 (Large current region) | 0.6 to 60.0 A in 0.1 A steps ( 1 A rating) 3.0 to 300.0 A in 0.1 A steps (5A rating) |
| DIFL-Slop1 (Small current region) | 10 to 50 \% |
| DIFL-Slop2 (Large current region) | 50 to 100 \% |
| Time setting for DIF | 0.00 to 100.00s in 0.01 s steps |
| Reference voltage | 100 to 120 V in 1V step |
| Operating time | Less than 1 cycle at $300 \%$ of DIFI1 |
| Resetting time | Less than 110 ms (for tripping output) Less than 40 ms (for signal output) |
| Zero-sequence Current Differential Protection for high-resistance earth |  |
| DIFGI | 0.05 to 1.00 A in 0.01 A steps (1A rating) 0.25 to 5.00 A in 0.01 A steps ( 5 A rating) |
| DIFG-Slop | 10 to 50 \% |
| Timer | 0.00 to 300.00 s in 0.01 s steps |
| Operating time | less than 45 ms |
| Resetting time | less than 100 ms |
| Charging Current Compensation |  |
| DIFL-IcC | 0.00 to 1.00 A in 0.01 A steps (1A rating) 0.00 to 5.00 A in 0.01 A steps ( 5 A rating) |
| Differential Current Supervision |  |
| DIFSV | 0.05 to 2.00 A in 0.01 A steps (1A rating) 0.25 to 10.00 A in 0.01 A steps ( 5 A rating) |
| Timer | 0 to 300s in 1s steps |
| DIF Guard characteristic |  |
| Overcurrent threshold | 0.02 to 50.00 A in 0.01 A steps ( 1 A rating) <br> 0.10 to 250.00 A in 0.01 A steps ( 5 A rating) |
| Rate of Overcurrent change threshold | 0.05 to 0.20 A in 0.01 A steps ( 1 A rating) <br> 0.25 to 1.00 A in 0.01 A steps ( 5 A rating) |
| Phase sequence Undervoltage threshold | 5.0 to 130.0 V in 0.1 V steps |
| Phase to Phase Undervoltage threshold | 5.0 to 130.0 V in 0.1 V steps |
| Rate of voltage change threshold | 1 to 20 V in 1 steps |
| DIFG Guard characteristic |  |
| Rate of Earth fault change threshold | 0.02 to 50.00 A in 0.01 A steps ( 1 A rating) <br> 0.10 to 250.00 A in 0.01 A steps (5 rating) |
| Phase Fault Distance Measuring Element |  |
| $Z^{*}$-Mho.Reach, Z $^{*}$-X.Reach and Z $^{*}$-R.Reach (Z1S, | 0.10 to $500.00 \Omega$ in $0.01 \Omega$ steps (1A rating) |
| Z1XS, Z2S, Z3S, Z4S, Z5S, ZCSF, ZCSR) | 0.01 to $100.00 \Omega$ in $0.01 \Omega$ steps ( 5 A rating) |
| Characteristic angle | $30^{\circ}$ to $90^{\circ}$ in $1^{\circ}$ steps |
| $Z^{*}$-Mho.Angle and $Z^{*}$-R.Angle (Z1S, Z1XS, Z2S, Z3S, Z4S, Z5S, ZCSF, ZCSR) |  |
| $Z^{*}$ - DirX.Angle and $Z^{*}$-DirR.Angle (Z1S, Z1XS, Z2S, Z3S, Z4S, Z5S, ZCSF, ZCSR) | $0^{\circ}$ to $60^{\circ}$ in $1^{\circ}$ steps |
| ZSF-X.GrAngle1 and ZSR-X.GrAngle1 | $0^{\circ}$ to $45^{\circ}$ in $1^{\circ}$ steps |
| ZSF-X.GrAngle2 and ZSR-X.GrAngle2 | $45^{\circ}$ to $90^{\circ}$ in $1^{\circ}$ steps |


| Earth Fault Distance Measuring Element |  |
| :---: | :---: |
| $Z^{*}$-Mho.Reach, $Z^{*}$-X.Reach and $Z^{*}$-R.Reach (Z1G, Z1XG, Z2G, Z3G, Z4G, Z5G, ZCGF, ZCGR) <br> Characteristic angle <br> $Z^{*}-M h o$.Angle and $Z^{*}$-R.Angle (Z1G, Z1XG, Z2G, Z3G, Z4G, Z5G, ZCGF, ZCGR) <br> $Z^{*}$ - $\operatorname{DirX.Angle~and~} Z^{*}$-DirR.Angle (Z1G, Z1XG, Z2G, Z3G, Z4G, Z5G, ZCGF, ZCGR) <br> ZGF-X.GrAngle1 and ZGR-X.GrAngle1 <br> ZGF-X.GrAngle2 and ZGR-X.GrAngle2 | ```0.10 to 500.00\Omega in 0.01\Omega steps (1A rating) 0.01 to }100.00\Omega\mathrm{ in 0.01 }\Omega\mathrm{ steps (5A rating) 30}\mathrm{ to }9\mp@subsup{0}{}{\circ}\mathrm{ in }\mp@subsup{1}{}{\circ}\mathrm{ steps 0}\mathrm{ 秋 }6\mp@subsup{0}{}{\circ}\mathrm{ in }\mp@subsup{1}{}{\circ}\mathrm{ steps 0 45}\mathrm{ to }9\mp@subsup{0}{}{\circ}\mathrm{ in }\mp@subsup{1}{}{\circ}\mathrm{ steps``` |
| Timer Setting |  |
| Time setting of Z1S, Z1XS, Z2S, Z3S, Z4S, Z5S, Z1G, Z1XG, Z2G, Z3G, Z4G, Z5G | 0.00 to 100.00 s in 0.01 steps |
| Overcurrent Element for Guard |  |
| Overcurrent elements $Z^{*}$ _OCFS for supervision distance measuring elements (Z1S, Z1XS, Z2S, Z3S, Z4S, Z5S, Z1G, Z1XG, Z2G, Z3G, Z4G, Z5G) | 0.02 to 5.00 A in 0.01 A steps ( 1 A rating) <br> 0.10 to 25.00 A in 0.01 A steps ( 5 A rating) |
| Command Protection Distance Scheme |  |
| Time for current reverse block Coordination time for BOP scheme Delayed drop-off timer | 0.00 to 10.00 s in 0.01 s steps <br> 0 to 50 ms in 1 ms steps <br> 0.00 to 1.00 s in 0.01 s steps |
| Command Protection Earth Fault Scheme |  |
| Time for delay trip <br> Time for current reverse block Coordination time for BOP scheme delayed drop-off timer | $0.00-0.30$ s in 0.01 s steps 0.00 to 10.00 s in 0.01 s steps 0 to 50 ms in 1 ms steps 0.00 to 1.00 s in 0.01 s steps |
| Power Swing Block |  |
| Detection zone (PSBGS) <br> Detection timer (TPSBS) | 2.50 to $75.00 \Omega$ in $0.01 \Omega$ steps (1A rating) 0.50 to $15.00 \Omega$ in $0.01 \Omega$ steps (5A rating) |
| Load Encroachment |  |
| Minimum load resistance (LESR, LESL) <br> Maximum load angle (LESR-Angle, LESL-Angle) | 0.10 to $500.00 \Omega$ in $0.01 \Omega$ steps (1A rating) <br> 0.01 to $100.00 \Omega$ in $0.01 \Omega$ steps (5A rating) <br> $5^{\circ}$ to $75^{\circ}$ in $1^{\circ}$ steps |
| Charging Current Compensation |  |
| Charging current compensation for distance relay <br> Rated voltage for charging current compensation | 0.00 to 1.00 A in 0.01 A steps ( 1 A rating) 0.00 to 5.00 A in 0.01 A steps ( 5 A rating) 100 to 120 V in 1 V steps |
| Minimum Operating Current |  |
| Current <br> Earth fault current | 0.08A fixed (1A relay) <br> 0.4A fixed (5A relay) <br> 0.10 to 1.00 A in 0.01 A steps $(1 \mathrm{~A}$ rating) <br> 0.50 to 5.00 A in 0.01 A steps ( 5 A rating) |
| Switch-on-to-fault Protection |  |
| Overcurrent threshold | 0.02 to. 5.00 A in 0.01 A steps ( 1 A rating) <br> 0.10 to 15.00 A in 0.01 A steps ( 5 A rating) |
| Stub Protection |  |
| Overcurrent threshold | 0.02 to 5.00 A in 0.01 A steps ( 1 A rating) <br> 0.10 to 15.00 A in 0.01 A steps ( 5 A rating) |


| Out-of-step Protection (Out of step tripping (voltage phase comparison) |  |
| :---: | :---: |
| Out-of-step trip | OFF / TRIP / BO(separated from other trip signals) |
| Out-of-step Protection (impedance locus) |  |
| Resistive reach (at Right side) | 15.00 to $150.00 \Omega$ in $0.01 \Omega$ steps (1A rating) 3.000 to $30.000 \Omega$ in $0.01 \Omega$ steps (5A rating) |
| Resistive reach (at Left side) | 5.00 to $50.00 \Omega$ in $0.01 \Omega$ steps (1A rating) <br> 1.000 to $10.000 \Omega$ in $0.01 \Omega$ steps (5A rating) |
| Resistive reach (at Forward) | 5.00 to $250.00 \Omega$ in $0.01 \Omega$ steps (1A rating) 1.000 to $50.000 \Omega$ in $0.001 \Omega$ steps (5A rating) |
| Resistive reach (at Backward) | 1.0 to $50.00 \Omega$ in $0.01 \Omega$ steps (1A rating) 0.200 to $10.000 \Omega$ in $0.001 \Omega$ steps( 5 A rating) |
| Detection time | 0.01 to 1.00 s in 0.01 s steps |
| Breaker Failure (BF) Protection |  |
| Overcurrent element | 0.1 to 2.0 A in 0.1 A steps ( 1 A rating) 0.5 to 10.0 A in 0.1 A steps ( 5 A rating) |
| BF timer for retry-trip of failed breaker | 50 to 500 ms in 1 ms steps |
| BF timer for related breaker trip | 50 to 500 ms in 1 ms steps |
| Non-directional and Directional Overcurrent Protection |  |
| $1^{\text {st }}, 2^{\text {nd }}, 3^{\text {rd }}, 4^{\text {th }}$ Definite time overcurrent threshold | 0.02 to 50.00 A in 0.01 A steps ( 1 A rating) <br> 0.10 to 250.00 A in 0.01 A steps ( 5 A rating) |
| $1^{\text {st }}, 2^{\text {nd }}, 3^{\text {rd }}, 4^{\text {th }}$ Inverse time overcurrent threshold | 0.02 to 5.00 A in 0.01 A steps ( 1 A rating) <br> 0.10 to 25.00 A in 0.01 A steps ( 5 A rating) |
| Direction characteristic | Non Directional / Forward / Backward |
| Polarising voltage | 1.0 V (fixed) |
| Characteristic angle | 0 to 180 deg in 1 deg steps |
| Delay type | DT / IEC-NI / IEC-VI / IEC-EI / UK-LTI / IEEE-MI / IEEE-VI / IEEE-EI / US-CO2 / US-CO8 / Original |
| Drop-out/pick-up ratio | 10 to $100 \%$ in $1 \%$ steps |
| DTL delay | 0.00 to 300.00 s in 0.01 s steps |
| IDMTL Time Multiplier Setting TMS | 0.010 to 50.000 in 0.001 steps |
| Reset type | Definite Time or Dependent Time |
| Reset definite delay | 0.00 to 300.00s in 0.01 s steps |
| Reset Time Multiplier Setting RTMS | 0.010 to 50.000 in 0.001 steps |
| Non-directional and Directional Earth Fault Protection |  |
| $1^{\text {st }}, 2^{\text {nd }}, 3^{\text {rd }}, 4^{\text {th }}$ Definite time earth fault threshold | 0.02 to 50.00 A in 0.01 A steps ( 1 A rating) <br> 0.10 to 250.00 A in 0.01 A steps ( 5 A rating) |
| $1^{\text {st }}, 2^{\text {nd }}, 3^{\text {rd }}, 4^{\text {th }}$ Inverse time earth fault threshold | 0.02 to 5.00 A in 0.01 A steps ( 1 A rating) <br> 0.10 to 25.00 A in 0.01 A steps ( 5 A rating) |
| Direction characteristic | Non Directional / Forward / Backward |
| Characteristic angle | 0 to $180^{\circ}$ in $1^{\circ}$ steps (310 lags for -3 V 0 ) |
| Polarising voltage (3V0) | 0.5 to 100.0V in 0.1 V steps |
| Delay type | DT / IEC-NI / IEC-VI / IEC-EI / UK-LTI / IEEE-MI / IEEE-VI / IEEE-EI / US-CO2 / US-CO8 / Original |
| Drop-out/pick-up ratio | 10 to $100 \%$ in $1 \%$ steps |
| DTL delay | 0.00 to 300.00 s in 0.01 s steps |
| IDMTL Time Multiplier Setting TMS | 0.010 to 50.000 in 0.001 steps |
| Reset type | Definite Time or Dependent Time |
| Reset definite delay | 0.00 to 300.00 s in 0.01 s steps |
| Reset Time Multiplier Setting RTMS | 0.010 to 50.000 in 0.001 steps |


| Non-directional and Directional Negative Sequence Phase Overcurrent (NOC) Protection |  |
| :---: | :---: |
| $1{ }^{\text {st }}, 2^{\text {nd }}, 3^{\text {rd }}, 4^{\text {th }}$ Definite time NOC threshold | 0.02 to 50.00 A in 0.01 A steps ( 1 A rating) <br> 0.10 to 250.00 A in 0.01 A steps ( 5 A rating) |
| $1^{\text {st }}, 2^{\text {nd }}, 3^{\text {rd }}, 4^{\text {th }}$ Inverse time NOC threshold | 0.02 to 5.00 A in 0.01 A steps ( 1 A rating) <br> 0.10 to 25.00 A in 0.01 A steps (5 rating) |
| Direction characteristic | Non Directional / Forward / Backward |
| Characteristic angle | 0 to $180^{\circ}$ in $1^{\circ}$ steps (310 lags for -3 V 0 ) |
| Polarising voltage | 0.5 to 25.0 V in 0.1 V steps |
| Delay type | DT / IEC-NI / IEC-VI / IEC-EI / UK-LTI / IEEE-MI / IEEE-VI / IEEE-EI / US-CO2 / US-CO8 / Original |
| Drop-out/pick-up ratio | 10 to $100 \%$ in $1 \%$ steps |
| DTL delay | 0.00 to 300.00 s in 0.01 s steps |
| IDMTL Time Multiplier Setting TMS | 0.010 to 50.000 in 0.001 steps |
| Reset type | Definite Time or Dependent Time |
| Reset definite delay | 0.00 to 300.00 s in 0.01 s steps |
| Reset Time Multiplier Setting RTMS | 0.010 to 50.000 in 0.001 steps |
| Inrush Current Detection |  |
| Second harmonic detection | 10 to 50\% in 1\% steps |
| Inrush current thresholds | 0.10 to 5.00 A in 0.01 A steps ( 1 A rating) 0.5 to 25.0 A in 0.1 A steps ( 5 A rating) |
| Thermal overload Protection |  |
| Thermal setting (THM = k.IFLC) | $0.40-2.00 \mathrm{~A}$ in 0.01 A steps (1A rating) $2.0-10.0 \mathrm{~A}$ in 0.1 A steps (5 rating) |
| Time constant ( $\tau$ ) | $0.5-500.0 \mathrm{mins}$ in 0.1 min steps |
| Thermal alarm | OFF, $50 \%$ to $100 \%$ in $1 \%$ steps |
| Pre-load current setting | $0.00-1.00 \mathrm{~A}$ in 0.01 A steps ( 1 A rating) $0.0-5.0 \mathrm{~A}$ in 0.1 A steps (5 rating) |
| Broken Conductor Detection |  |
| Broken conductor threshold DTL delay | 0.10 to 1.00 in 0.01 steps 0.00 to 300.00 s in 0.01 s steps |
| Phase Overvoltage Protection |  |
| $11^{\text {st }}, 2^{\text {nd }}$ overvoltage threshold | 1.0 to 220.0 V in 0.1 V steps |
| Delay type | DTL, IDMT, Original |
| Drop-out/pick-up ratio | 10 to $100 \%$ in $1 \%$ steps |
| DTL delay | 0.00 to 300.00 s in 0.01 s steps |
| IDMTL Time Multiplier Setting TMS | 0.010 to 100.000 in 0.001 steps |
| Reset delay | 0.0 to 300.0 s in 0.1 s steps |
| Phase to Phase Overvoltage Protection |  |
| $1{ }^{\text {st }}, 2^{\text {nd }}$ overvoltage threshold | 1.0 to 220.0 V in 0.1 V steps |
| Delay type | DTL, IDMT, Original |
| Drop-out/pick-up ratio | 10 to $100 \%$ in $1 \%$ steps |
| DTL delay | 0.00 to 300.00 s in 0.01 s steps |
| IDMTL Time Multiplier Setting TMS | 0.010 to 100.000 in 0.001 steps |
| Reset delay | 0.0 to 300.0 s in 0.1 s steps |


| Phase Undervoltage Protection |  |
| :---: | :---: |
| $1^{\text {st }}, 2^{\text {nd }}$ undervoltage threshold <br> Delay type <br> Drop-out/pick-up ratio <br> DTL delay <br> IDMTL Time Multiplier Setting TMS <br> Reset delay <br> Undervoltage block threshold <br> Undervoltage block delay | 5.0 to 130.0 V in 0.1 V steps DTL, IDMT, Original 100 to $120 \%$ in $1 \%$ steps 0.00 to 300.00 s in 0.01 s steps 0.010 to 100.000 in 0.001 steps 0.0 to 300.0 s in 0.1 s steps 5.0 to 20.0 V in 0.1 V steps 0.00 to 300.00 s in 0.01 s steps |
| Phase to Phase Undervoltage Protection |  |
| $1^{\text {st }}, 2^{\text {nd }}$ undervoltage threshold <br> Delay type <br> Drop-out/pick-up ratio <br> DTL delay <br> IDMTL Time Multiplier Setting TMS <br> Reset delay <br> Undervoltage block threshold <br> Undervoltage block delay | 5.0 to 130.0 V in 0.1 V steps <br> DTL, IDMT, Original 100 to $120 \%$ in $1 \%$ steps 0.00 to 300.00 s in 0.01 s steps 0.010 to 100.000 in 0.001 steps 0.0 to 300.0 s in 0.1 s steps 5.0 to 20.0 V in 0.1 V steps 0.00 to 300.00 s in 0.01 s steps |
| Under/Over Frequency Protection |  |
| $1^{\text {st }}-4^{\text {th }}$ under/overfrequency threshold <br> DTL delay: <br> Frequency UV Block | $\begin{aligned} & \left(F_{\text {nom }}-10.00 \mathrm{~Hz}\right)-\left(F_{\text {nom }}+10.00 \mathrm{~Hz}\right) \text { in } 0.01 \mathrm{~Hz} \text { steps } \\ & \text { Fnom: nominal frequency }^{0.00-300.00 \mathrm{~s} \text { in } 0.01 \mathrm{~s} \text { steps }} \\ & 40.0-100.0 \mathrm{~V} \text { in } 0.1 \mathrm{~V} \text { steps } \end{aligned}$ |
| Autoreclosing |  |
| Number of shots <br> Dead time for single-phase autoreclose <br> Dead time for three-phase autoreclose <br> Multi-shot dead line time <br> Reclaim time <br> Pulse width of reclosing signal output <br> Autoreclose reset time <br> Reset time for developing fault <br> Follower breaker autoreclose delay time | 1 to 5 shots <br> 0.01 to 300.00 s in 0.01 s steps <br> 0.01 to 300.00 s in 0.01 s steps <br> 0.01 to 300.00 s in 0.01 s steps <br> 0.0 to 600.0 s in 0.1 s steps <br> 0.01 to 10.00 s in 0.01 s steps <br> 0.01 to 310.00 s in 0.01 s steps <br> 0.01 to 300.00 s in 0.01 s steps <br> 0.01 to 300.00 s in 0.01 s steps |
| Voltage and Synchronism Check |  |
| Synchronism check angle <br> UV element <br> OV element <br> Busbar or line dead check <br> Busbar or line live check <br> Synchronism check time <br> Voltage check time | $0^{\circ}$ to $75^{\circ}$ in $1^{\circ}$ steps <br> 10 to 150 V in 1 V steps <br> 10 to 150 V in 1 V steps <br> 10 to 150 V in 1 V steps <br> 10 to 150 V in 1 V steps <br> 0.01 to 100.00 s in 0.01 s steps <br> 0.01 to 100.00 s in 0.01 s steps |
| Voltage Transformer Failure Supervisio |  |
| Undervoltage element (phase-to-phase) Undervoltage element (phase-to-earth) Current change detection element <br> Residual voltage element <br> Residual current element | 50 to 100 V in 1 V steps <br> 10 to 60 V in 1 V steps <br> 0.1 A fixed (1A rating) <br> 0.5A fixed (5A rating) <br> 20V fixed <br> Common use with earth fault detection element |


| Fault Locator |  |
| :--- | :--- |
| Line reactance and resistance setting | 0.0 to $999.9 \Omega$ in $0.1 \Omega$ steps (1A rating) |
|  | 0.00 to $199.99 \Omega$ in $0.01 \Omega$ steps ( 5 A rating) |
| Line length | 0.0 to 399.9 km in 0.1 km steps |
| Correction factor of impedance between lines | 80 to $120 \%$ in $1 \%$ steps |
| Correction factor of impedance between in each | 80 to $120 \%$ in $1 \%$ steps |
| phase |  |
| Accuracy | $\pm 0.4 \mathrm{~km}$ (up to 20 km , without fault at near end) |
|  | $\pm 2 \%$ (up to 399.9 km , without fault at near end) |
| Minimum measuring cycles | 2.5 cycles |
| Metering Function | Accuracy $\pm 0.5 \%$ (at rating) |
| AC Current | Accuracy $\pm 0.5 \%$ (at rating) |
| AC Voltage | Accuracy $\pm 1.0 \%$ (at rating) |
| Energy (Wh, varh) | Accuracy $\pm 1.0 \%$ (at rating when power quantities being fed) |
| Power (P, Q) | Accuracy $\pm 0.03 \mathrm{~Hz}$ |
| Frequency | SNTP |
| GPS Time Synchronisation |  |
| Protocol |  |

ORDERING INFORMATION

1. Line Differential protection relay
[Hardware selection]



Note:
(*1) Binary inputs are intended for use with DC power source only.
The power supply supervision function is intended for use with DC power source only. It should be disabled when AC power supply is applied in order to prevent spurious alarms.
(*2) For PRP/HSR/RSTP protocol with IEC 61850, choose "L" or "N" code at position E. For hot/standby configuration or single port configuration with IEC 61850, choose other codes at position E.

(*3) For 19" rack panel mounting, accessories of joint kits are available. (See Figure 20)
Please contact with our sales staffs when you require user configurable models that are not indicated in the ordering sheet above.

## [Software selection]


(*1) For PRP/HSR/RSTP protocol with IEC 61850, choose "L" or "N" code at position E. For hot/standby configuration or single port configuration with IEC 61850, choose other codes at position E.

Note: Software selection codes "7", "E", "F" and "9" are common with hardware selection codes.

## Number of BI/BO

BI/BO $1 \times$ I/O module


## BI/BO $2 \times$ I/O module



BI/BO $3 \times \mathrm{I} / \mathrm{O}$ module

| Number of BI/BO |  |  |  |  |  |  | Ordering No. <br> (Position "A" to "B") | Configuration |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | O |  |  |  |
| 15 | - | - | 6 | 12 | 18 | - | 31 | 1xBO1+1xBIO1+1xBIO3 |
| 20 | - | - | 6 | 9 | 16 | - | 32 | $1 \times \mathrm{BO} 1+1 \times \mathrm{BIO} 2+1 \times \mathrm{BIO} 3$ |
| 23 | - | - | 12 | 6 | 8 | - | 33 | 1xBIO1+2xBIO3 |
| 26 | - | - | 6 | 6 | 14 | - | 34 | 1xBI1+1xBO1+1xBIO3 (*1) |
| 8 | - | 32 | 6 | 6 | 14 | - | 35 | $1 \times \mathrm{BI} 3+1 \times \mathrm{BO} 1+1 \times \mathrm{BIO} 3$ |
| 24 | - | - | 18 | - | 6 | - | 36 | 3xBIO3 |
| 25 | - | - | - | 12 | 16 | - | 37 | $1 \times \mathrm{BI} 1+1 \times \mathrm{BO} 1+1 \times \mathrm{BIO} 1$ |
| 36 | - | - | - | 6 | 12 | - | 39 | 2xBI1+1xBO1 |
| - | 24 | - | - | 6 | 12 | - | 3A | $2 \times \mathrm{BI} 2+1 \times \mathrm{BO} 1$ |
| 7 | - | 32 | - | 6 | 4 | 16 | 3C | $1 \times \mathrm{BI} 3+1 \times \mathrm{BIO} 1+1 \times \mathrm{BO} 2$ |
| 7 | - | 32 | - | 12 | 16 | - | 3D | $1 \times \mathrm{BI} 3+1 \times \mathrm{BO} 1+1 \times \mathrm{BIO} 1$ |
| - | - | 32 | - | 6 | 12 | 16 | 3E | $1 \times \mathrm{BI} 3+1 \times \mathrm{BO} 1+1 \times \mathrm{BO} 2$ |
| 16 | - | - | 12 | 6 | 16 | - | 3G | 1xBO1+2xBIO3 |
| 26 | - | - | 6 | 6 | 14 | - | 3J | 1xBO1+1xBIO3+1xBI1 (*1) |
| - | - | 64 | - | 6 | 12 | - | 3K | $2 \times \mathrm{BI} 3+1 \times \mathrm{BO} 1$ |
| 14 | - | 32 | - | 12 | 8 | - | 3L | 1xBI3+2xBIO1 |
| - | - | 96 | - | - | - | - | 3M | 3xBI3 |
| 8 | 12 | - | 6 | 6 | 14 | - | 3N | $1 \times \mathrm{BI} 2+1 \times \mathrm{BO} 1+1 \times \mathrm{BIO} 3$ |
| - | - | 32 | - | 12 | 24 | - | 3P | $1 \times \mathrm{BI} 3+2 \mathrm{XBO} 1$ |
| 36 | - | - | - | - | - | 16 | 3Q | $2 \mathrm{xBI} 1+1 \mathrm{xBO} 2$ |
| 16 | 12 | - | 12 | - | 4 | - | 3 S | $1 \times \mathrm{BI} 2+2 \mathrm{xBIO} 3$ |
| 18 | 12 |  |  | 6 | 12 |  | 3 T | 1xBI1+1xBI2+1xBO1 |
| 12 |  | 32 |  | 9 | 14 |  | 3 U | $1 \times \mathrm{BI} 3+1 \times \mathrm{BO} 1+1 \times \mathrm{BIO} 2$ |
|  |  |  |  |  |  |  |  |  |

Note:
(*1) The difference between ' 34 ' and ' 3 J ' is the implementation location.

BI/BO $4 \times \mathrm{I} / \mathrm{O}$ modules


Note:
(*2) The difference between ' 41 ' and ' 48 ' is the implementation location.

BI/BO $5 \times \mathrm{I} / \mathrm{O}$ modules


BI/BO $6 \times \mathrm{I} / \mathrm{O}$ modules


BI/BO $7 \times \mathrm{I} / \mathrm{O}$ modules

$\mathrm{BI} / \mathrm{BO} 8 \times \mathrm{I} / \mathrm{O}$ modules


## Communication Table

1CH Communication for Protection (Position " C " is set to " 1 ")

| Communication Type | Ordering No. <br> (Position "D") |
| :--- | :---: |
| Protection signal GI 2km Class (C37.94) | $\mathbf{1}$ |
| Protection signal SM 30km Class | $\mathbf{2}$ |
| Protection signal DSF 80km Class | $\mathbf{3}$ |

2CH Communication for Protection (Position " C " is set to " 2 ")

| Communication Type | Ordering No. <br> (Position "D") |
| :--- | :---: |
| Protection signal Gl 2km Class (C37.94) x2ch | $\mathbf{1}$ |
| Protection signal SM 30km Class x2ch | $\mathbf{2}$ |
| Protection signal DSF 80km Class x2ch | $\mathbf{3}$ |
| Protection signal GI 2km Class (C37.94) x1ch <br> Protection signal SM 30km Class x1ch | $\mathbf{4}$ |
| Protection signal Gl 2km Class (C37.94) x1ch <br> Protection signal DSF 80km Class x1ch | $\mathbf{5}$ |
| Protection signal SM 30km Class x1ch <br> Protection signal DSF 80km Class x1ch | $\mathbf{6}$ |

## Communication Port Table

When the code $[C]=1 \quad$ (Number of protection signalling = 1 )

| Serial and/or Ethernet and/or Time Synch port |  |  |  |  |  | Ordering No. <br> (Position "E" to "F") | Remark |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| IEC 60870-5-103 |  | IEC 61850-8-1 |  |  |  |  |  |
| $\begin{aligned} & \infty \\ & \stackrel{\sim}{\infty} \\ & \underset{\sim}{\infty} \end{aligned}$ |  | 100Base-FX (*1) |  |  | ¢ $\underline{\text { v }}$ $\underline{\underline{\underline{x}}}$ |  |  |
|  |  | 1 |  |  |  | 14 |  |
|  |  |  | 1 |  |  | 1 J |  |
|  |  |  |  | 1 |  | 1K |  |
|  |  | 1 |  |  | 1 | 34 |  |
|  |  |  | 1 |  | 1 | 3 J |  |
|  |  |  |  | 1 | 1 | 3K |  |
|  |  | 2 |  |  |  | 46 | Hot/Standby |
| 1 |  | 1 |  |  |  | 4 C |  |
|  | 1 | 1 |  |  |  | 4G |  |
|  |  |  | 2 |  |  | 4L | Hot/Standby |
|  |  |  |  | 2 |  | 4M | Hot/Standby |
| 1 |  |  | 1 |  |  | 4 N |  |
| 1 |  |  |  | 1 |  | 4Q |  |
|  | 1 |  | 1 |  |  | 4S |  |
|  | 1 |  |  | 1 |  | 4 U |  |
|  |  | 2 |  |  | 1 | 66 | Hot/Standby |
| 1 |  | 1 |  |  | 1 | 6 C |  |
|  | 1 | 1 |  |  | 1 | 6G |  |
|  |  |  | 2 |  | 1 | 6L |  |
|  |  |  |  | 2 | 1 | 6M | Hot/Standby |



Note:
(*1) When 100Base-FX is selected, 2 slots out of 5 slots for communication ports are used regardless the number of 100Base-FX (1 or 2). Therefore, the total number for communication ports needs to be cared.

When the code $[C]=2 \quad$ (Number of protection signalling = 2 )


## Note:

(*1) When 100Base-FX is selected, 2 slots out of 5 slots for communication ports are used regardless the number of 100Base-FX (1 or 2). Therefore, the total number for communication ports needs to be cared.

FUNCTION TABLE


| Function Block | Protection function |  | Ordering No. (Position "G \& N") |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | 33 | 37 |
| FRQ | 81 | Frequency protection | $\bullet$ | $\bullet$ |
| OSTV | 56V | Out of step tripping by voltage(*1) | $\bullet$ | $\bullet$ |
| ICD | ICD | Inrush current detection function | $\bullet$ | $\bullet$ |
| FS | FS | Fail-safe function | $\bullet$ | $\bullet$ |
| VTF | VTF | VTF detection function | $\bullet$ | $\bullet$ |
| CTF | CTF | CTF detection function | $\bullet$ | $\bullet$ |
| FL-Z | 21FL | Fault locator | $\bullet$ | $\bullet$ |
| FL-A | FL | Fault locator | $\bullet$ | $\bullet$ |
| TRC | 94 | Trip circuit | $\bullet$ | $\bullet$ |
| ARC | 79 | Autoreclosing function | $\bullet$ | $\bullet$ |
| VCHK | 25 | Voltage check for autoreclosing | $\bullet$ | $\bullet$ |
| General Control | LEDR | LED reset | $\bullet$ | $\bullet$ |
|  | GCNT | Counter function for the general | $\bullet$ | $\bullet$ |
|  | MDCTRL | Mode control function | - | $\bullet$ |
| Control and monitor | SPOS | Single position device function |  | $\bullet$ |
|  | DPSY | Double position controller with synchronizing |  | $\bullet$ |
|  | SOTFSW | Software switch controller |  | - |
|  | OPTIM | Operation time reset |  | $\bullet$ |
|  | $\begin{aligned} & \text { TOTALTI } \\ & \mathrm{M} \\ & \hline \end{aligned}$ | Total time measurement |  | $\bullet$ |
|  | SYNDIF | Synchronizing check for different network |  | $\bullet$ |
|  | INTERL OCK | Software interlock |  | $\bullet$ |
|  | DPOS | Double position device function |  | $\bullet$ |
|  | TPOS | Three position device function |  | $\bullet$ |
|  | GENBI | Event detection function for general Bls |  | $\bullet$ |
|  | ASEQ | Automatic sequence control function |  | $\bullet$ |
|  |  |  | 0 0 0 0 |  |

## 2. Interface Converter




Note: For a rack mount unit, there are holes for joint kits assembling on top and bottom of the unit.

Figure 16 - Dimension and Panel Cut-out - $1 / 2 \times 19^{\prime \prime}$ case size
(when compression plug type terminals are applied)

DIMENSION AND PANEL CUT-OUT (3/4 size)


Note: For a rack mount unit, there are holes for joint kits assembling on top and bottom of the unit.

Figure 17 - Dimension and Panel Cut-out - $3 / 4 \times 19^{\prime \prime}$ case size for flush mounting type (when compression plug type terminals are applied)


Note: For a rack mount unit, there are holes for joint kits assembling on top and bottom of the unit.

Figure 18 - Dimension and Panel Cut-out - $1 / 1 \times 19$ " case size for flush mounting type (when compression plug type terminals are applied)

## DIMENSION AND PANEL CUT-OUT (Interface Converter)



Figure 19 - Outline of Interface Converter GIF200
<Panel mounting kits - only for compressed terminal type racks>

| Name | Code |
| :--- | :--- |
| Joint kits for single $1 / 2 \times 19^{\prime \prime}$ size rack | EP-204 |
| Joint kits for two $1 / 2 \times 19^{\prime \prime}$ size racks | EP-205 |
| Joint kits for single $3 / 4 \times 19^{\prime \prime}$ size rack | EP-206 |



Figure 20 - Joint kits example for 19" rack panel mounting

CONNECTIONS DIAGRAM

(*1) Fast BO
(*2) Semi-fast BO
(*3) Hybrid BO
(*4) Normal BO
(*5) Form-C BO

Figure 21 - Binary input board and binary output module for compression plug type

CONNECTIONS DIAGRAM

(*1) Fast BO
(*2) Semi-fast BO
(*3) Hybrid BO
(*4) Normal BO
(*5) Form-C BO

Figure 22 - Combined binary input and output module and DC power supply module for compression plug type

## CONNECTIONS DIAGRAM

## CT/VT module



Module no. 11
(CT x $9+\mathrm{VT} \times 5$ )


Module no. 12 (CT x $5+\mathrm{VT} \times 5$ )

Figure 23 - CT/VT module

## EXTERNAL CONNECTIONS DIAGRAM



Figure 24 - Typical external connection diagram (PCT: No.12, IO: BI1, BO1 and BIO3)

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